DR. ALEXANDER JAMES D. MCGREGOR

Robotics Mechanical Hardware Engineer

@ AlexanderJDMcGregor@gmail.com

(+61) 0451690607

Perth, WA

in linkedin.com/in/alexandermcg

PROFILE

I am currently a Mechanical Engineer in the Hardware Team at Advanced Navigation. I have an Engineering Doctorate in Robotics for Non-Destructive Evaluation from Strathclyde University sponsored by Eddyfi Technologies, and previously completed a MEng in Mechanical Engineering with Financial Management with distinction from Strathclyde University. I enjoy the challenge of finding real world solutions to difficult problems.

EDUCATION

Engineering Doctorate in Robotics for Inspection - EngD Strathclyde University

Glasgow, UK

- Doctorate on the development of a robotic positioning algorithm for inspection of pipes using accelerometers.
- Deployment of probabilistic sensor fusion algorithms to increase the accuracy of state estimation in a robotic positioning context.
- Matlab, C# and Python coding languages used throughout.
- Undertook various NDE courses as part of the RCNDE.
 Including Machine Learning for Acoustics, Data Science in Python and Signal Processing.

Mechanical Engineering with Financial Management - MEng Strathclyde University

Glasgow, UK

- Masters group project developing and prototyping a micro-turbine to generate electricity at pressure reduction stations in the gas network.
- Undertook a year studying in Spain with all classes in Spanish, obtaining a B2 level of Spanish.
- Dissertation on structural health monitoring of self-reinforcing composite materials using vibrational analysis.
- Dissertation on the implications of finance and the economy on engineering in industry.

Highschool - International Baccalaureate American British Academy

Sept 2009 - Aug 2011

Muscat, Oman

• 36 IB points.

PUBLICATIONS, PRESENTATIONS AND POSTERS

BINDT Conference

Title: Mobile Robotic Positioning for Pipe Inspection with Sensor Fusion

IEEE Sensors Journal

🛗 Jan 2020

Title: Determining Position and Orientation of a 3-Wheel Robot on a Pipe Using an Accelerometer doi: 10.1109/JSEN.2020.2964619

AIP QNDE Conference Proceedings

Purlington, Vermont, US

Title: Mobile Robot Positioning Using Accelerometers for Pipe Inspection

doi: 10.1063/1.5099794

RCNDE Annual Conference Presentation

May 2018

Paristol, UK

Title: Determining Orientation and Position on a Pipe using an IMU

BMVA Computer Vision Poster

Norwich, UK

Title: Robot Positioning on a Pipe Using

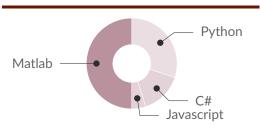
Gravity

Rolls Royce EngD Conference Poster

Oerby, UK

Title: Intelligent Crawler Robots for NDE

PROGRAMMING LANGUAGES



WORK EXPERIENCE

Mechanical Engineer

Advanced Navigation

Mar 2022 - Present

Perth. AU

- Working on the mechanical design of underwater AUVs
- Using Solidworks for designing parts and managing complex assemblies
- Work closely with the electrical and software teams to come up with innovative solutions in the subsea space
- Scope out work packages and work with the Product and Project teams to determine engineering requirements

Algorithm and Measurment Solutions Engineer

Siemens Mobility

Perth, AU

- Designed laser and camera units for condition monitoring of the public transport system to be installed at the Los Angeles Airport
- CAD using Inventor for the mechanical design for laser/camera calibration and validation systems
- Simulated and experimental validation of measurement concepts through rendering laser lines and capture of real image data to determine measurement accuracy of prototype systems.

Student Researcher

Eddyfi Technologies

Sep 2017 - Aug 2020

Swansea, UK

• Coded scripts in Python, C# and MatLab to clean an analyse data. I also characterised and tested various sensors and equipment for robotic positioning purposes.

Rotating Equipment Intern

Royal Dutch Shell

Jun - Sept 2015

Rijswijk, NL

• Literature and patent review of alternative compression technology as well as thermodynamic analysis and calculations for alternative compression technology.

Assistant Technitian

Sonovation

Aug 2013

Oosterhout, NL

• Aided to develop ultrasonic testing procedures and prepare samples for stainless steel welds inspection.

REFERENCES

References available on request.